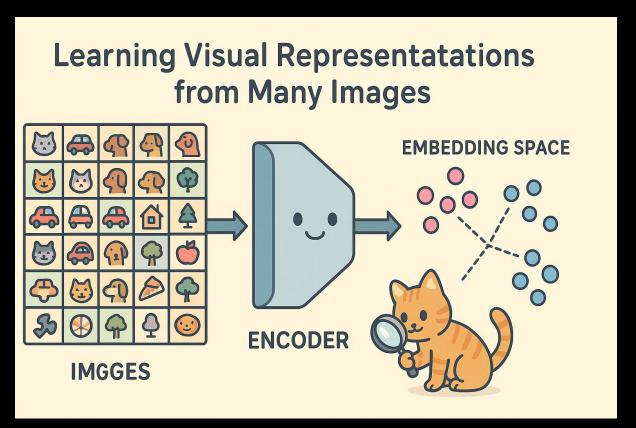
Visual Representation in the Multimodal Era

Shengbang Tong,



Self-Supervision

Self-Supervision

- MoCo, MAE, DINO

Language-Supervision:

- CLIP, SigLIP, MetaCLIP

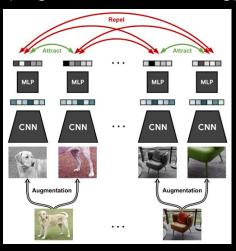
Self-Supervision

- MoCo, MAE, DINO
- Learn from images itself (augmentation, masking)

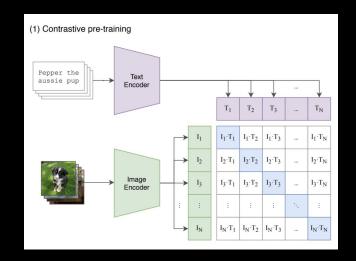
- CLIP, SigLIP, MetaCLIP
- Learn from language that "describe the image"

Self-Supervision

- MoCo, MAE, DINO
- Learn from images itself (augmentation, masking)



- CLIP, SigLIP, MetaCLIP
- Learn from language that "describe the image"



Self-Supervision

- MoCo, MAE, DINO
- Learn from images itself (augmentation, masking)
- Train on ImageNet-Like
 Data (million scale to hundred million scale)

- CLIP, SigLIP, MetaCLIP
- Learn from language that "describe the text"
- Train on Image-Text pairs crawled from the internet (400 million to 100 billion)

Self-Supervision

- MoCo, MAE, DINO
- Learn from images itself (augmentation, masking)
- Train on ImageNet-Like
 Data (million scale to
 hundred million scale)
- Good at <u>classification</u>, segmentation, depth estimation, etc

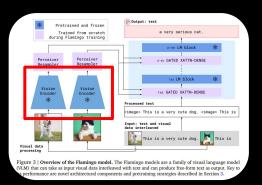
- CLIP, SigLIP, MetaCLIP
- Learn from language that "describe the text"
- Train on Image-Text pairs crawled from the internet (400 million to 100 billion)
- Good at <u>classification</u>, and widely used at backbone for multimodal models

Eyes Wide Shut? Exploring the Visual Shortcomings of Multimodal LLMs

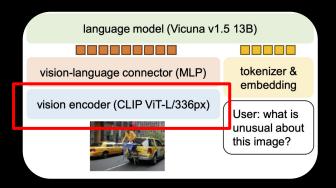
Shengbang Tong¹, Zhuang Liu², Yuexiang Zhai³, Yi Ma³, Yann LeCun¹, Saining Xie¹

¹NYU,²FAIR, Meta AI, ³UC Berkeley

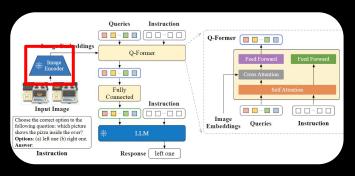
Recap on the MLLM Architecture



Flamingo [Alayrac, Jean-Baptiste, et al. 2022]

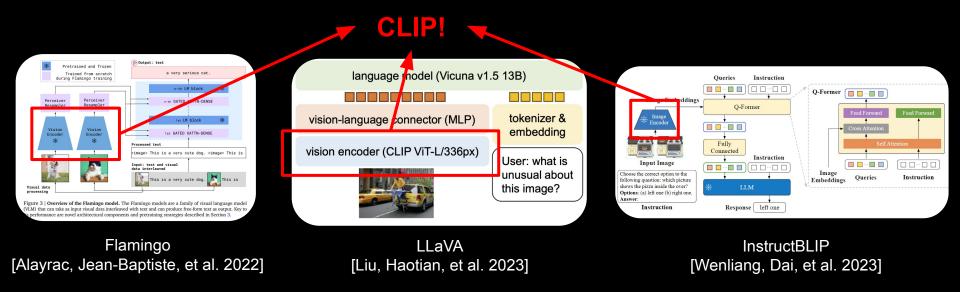


LLaVA [Liu, Haotian, et al. 2023]



InstructBLIP [Wenliang, Dai, et al. 2023]

Recap on the MLLM Architecture



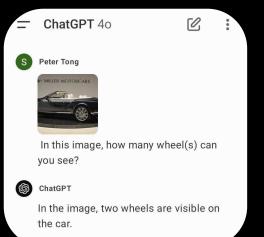
They all use a pretrained Vision Encoder, CLIP!

But MLLMs also make unexpected mistakes



From camera's perspective, is this dog facing left or right?

The dog in the image is facing to the right from the camera's perspective.





Q: Do you see any window in this image?

No, there are **no windows visible** in this image. The image shows a traditional re

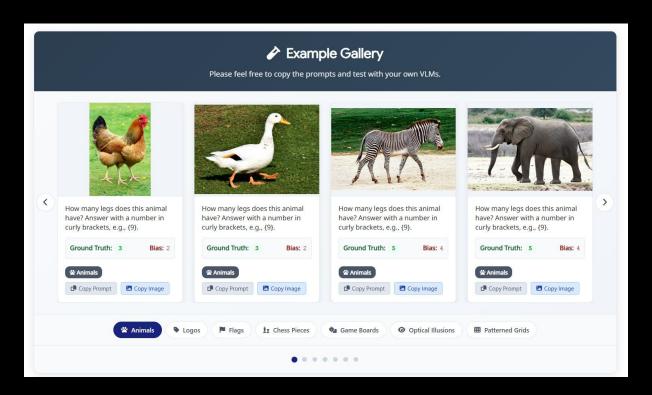
this image. The image shows a traditional red pillar box, which is a type of mailbox found in the United Kingdom.



Q: Is the door of the truck cab open?



But MLLMs also make unexpected mistakes



Agenda

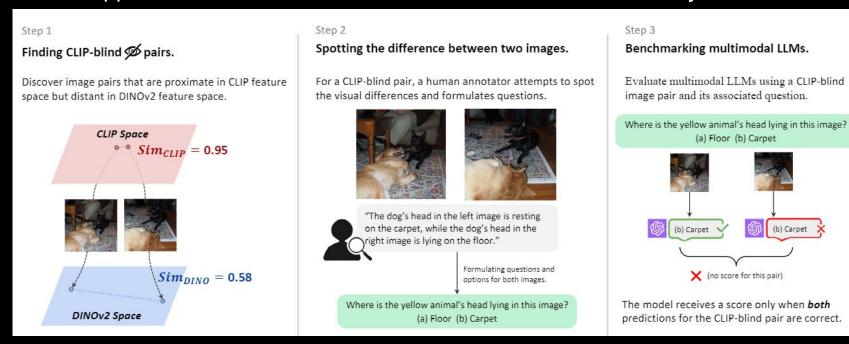
- How do we find these mistakes?

- Why do models make these mistakes?

How do we find these mistakes?

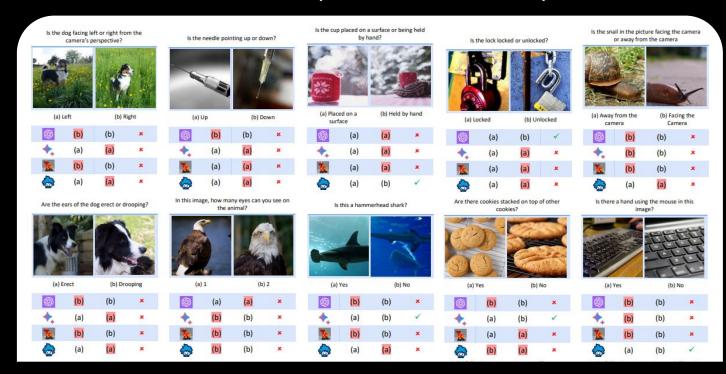
Finding CLIP-blind pairs

CLIP-blind pairs: If two images are encoded similarly by the CLIP model yet very different in visual appearance, then at least one of them has been inaccurately encoded.

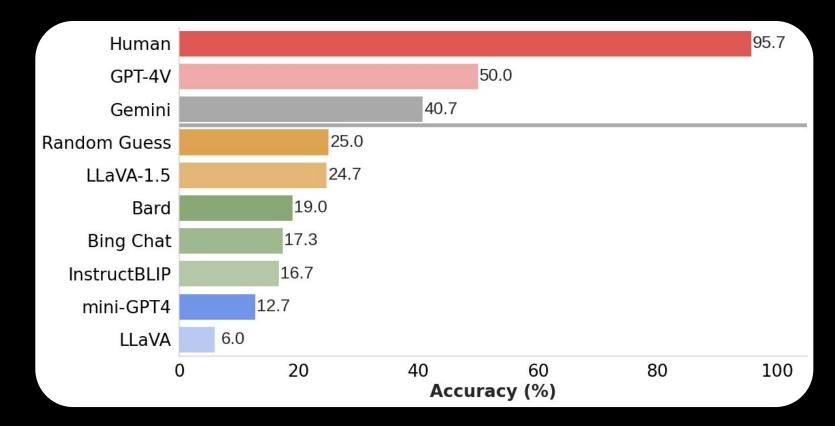


MMVP (MultiModal Visual Patterns) Benchmark

MMVP Benchmark: 150 CLIP-blind pairs & handcrafted questions



MMVP Benchmark Results



MMVP Benchmark Results

Capability	Benchmark	Seed 1.5-VL thinking	Seed 1.5-VL non-thinking	Gemini 2.5 Pro thinking	OpenAl o1 thinking	Claude 3.7 Sonnet thinking	OpenAl GPT-40 non-thinking	Qwen 2.5-VL 72B non-thinking
	MMMU	77.9	73.6	81.7	77.6	75.2*	70.7*	70.2
	MMMU-Pro	67.6	59.9	68.8*	66.4*	50.1*	54.5*	51.1
	MathVision	68.7	65.5	73.3*	63.2*	58.6*	31.2*	38.1
	OlympiadBench	65.0	60.4	69.8*	48.5*	54.2*	25.9*	35.9
Multimodal	MathVista	85.6	83.0	82.7*	71.8	74.5*	63.8*	74.8
reasoning	V^*	89.0	89.5	79.1*	69.7*	86.4*	73.9*	86.4
	VLM are Blind	92.1	90.8	84.3*	57.0*	69.0*	50.4*	69
	ZeroBench (main)	2	0	3*	0*	3*	0*	0
	ZeroBench (sub)	30.8	29.0	26.0*	20.2*	20.4*	19.6*	13.0
	VisuLogic	35.0	33.0	31.0*	29.0*	24.8*	26.3*	28.0
	RealWorldQA	78.4	77.0	78.0*	77.1*	67.8*	76.2*	75.7
	SimpleVQA	63.4	63.1	62.0*	58.8*	50.1*	52.4*	52.4
General	MMStar	77.8	76.2	77.5*	67.5*	68.8*	65.1*	70.8
visual question	MMBench-en	89.9	88.0	90.1*	83.8*	82.0*	84.3*	88.6
answering	MMBench-cn	89.1	88.1	89.7*	81.3*	82.7*	82.0*	87.9
and the second s	MMVP	69.3	70.7	70.7*	_†	_†	70.7*	66.7
'	HallusionBench	60.3	60.0	63.7*	55.6*	58.3*	56.2*	55.2

Why do models make these mistakes?

Finding Patterns in CLIP-blind Pairs

Questions in MMVP:



Finding Patterns in CLIP-blind Pairs

Questions in MMVP:





: Summarize Patterns

Finding Patterns in CLIP-blind Pairs

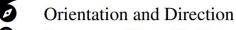
Questions in MMVP:





: Summarize Patterns

Visual Patterns:



Presence of Specific Features

State and Condition

1 Quantity and Count

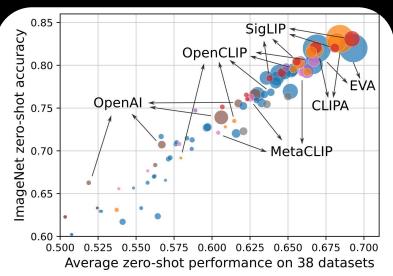
Positional and Relational Context

Color and Appearance

Structural and Physical Characteristics

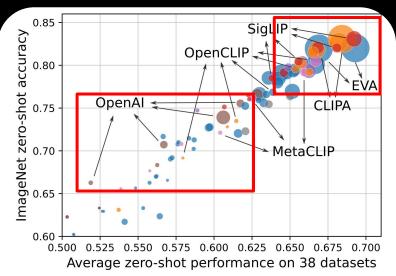
A Texts

Viewpoint and Perspective





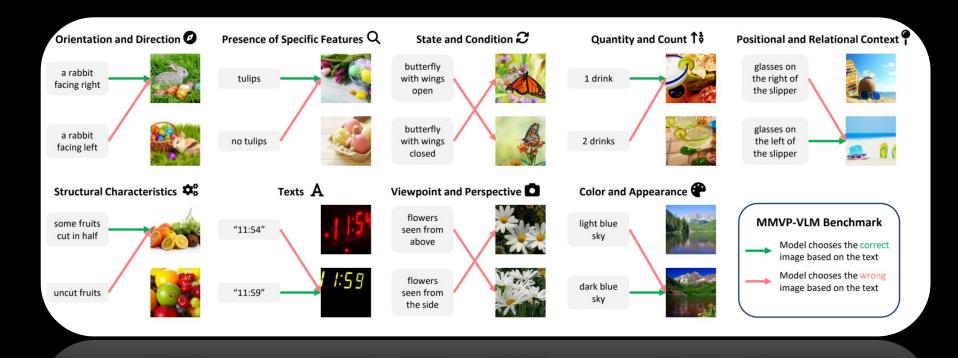
Does scaling up CLIP solves the problem?





Does scaling up CLIP solves the problem?

MMVP-VLM Benchmark



! ! !	Image Size	Params (M)	IN-1k ZeroShot	0	Q	2	13	9	•	\$ °	A	0	MMVP Average
OpenAI ViT-L-14 [35]	224^{2}	427.6	75.5	13.3	13.3	20.0	20.0	13.3	53.3	20.0	6.7	13.3	19.3
OpenAI ViT-L-14 [35]	336^{2}	427.9	76.6	0.0	20.0	40.0	20.0	6.7	20.0	33.3	6.7	33.3	20.0
SigLIP ViT-SO-14 [53]	224^{2}	877.4	82.0	26.7	20.0	53.3	40.0	20.0	66.7	40.0	20.0	53.3	37.8
SigLIP ViT-SO-14 [53]	384^{2}	878.0	83.1	20.0	26.7	60.0	33.3	13.3	66.7	33.3	26.7	53.3	37.0
DFN ViT-H-14 [9]	224^{2}	986.1	83.4	20.0	26.7	73.3	26.7	26.7	66.7	46.7	13.3	53.3	39.3
DFN ViT-H-14 [9]	378^{2}	986.7	84.4	13.3	20.0	53.3	33.3	26.7	66.7	40.0	20.0	40.0	34.8
MetaCLIP ViT-L-14 [49]	224^{2}	427.6	79.2	13.3	6.7	66.7	6.7	33.3	46.7	20.0	6.7	13.3	23.7
MetaCLIP ViT-H-14 [49]	224^{2}	986.1	80.6	6.7	13.3	60.0	13.3	6.7	53.3	26.7	13.3	33.3	25.2
EVA01 ViT-g-14 [43]	224^{2}	1136.4	78.5	6.7	26.7	40.0	6.7	13.3	66.7	13.3	13.3	20.0	23.0
EVA02 ViT-bigE-14+ [43]	224^{2}	5044.9	82.0	13.3	20.0	66.7	26.7	26.7	66.7	26.7	20.0	33.3	33.3

#1: Scaling up resolution does not help

	7.6												
I I	Image Size	Params (M)	IN-1k ZeroShot	0	Q	8	13	•	*	\$ °	A	0	MMVP Average
OpenAI ViT-L-14 [35]	224 ²	427.6	75.5	13.3	13.3	20.0	20.0	13.3	53.3	20.0	6.7	13.3	19.3
OpenAI ViT-L-14 [35]	336^{2}	427.9	76.6	0.0	20.0	40.0	20.0	6.7	20.0	33.3	6.7	33.3	20.0
SigLIP ViT-SO-14 [53]	224^{2}	877.4	82.0	26.7	20.0	53.3	40.0	20.0	66.7	40.0	20.0	53.3	37.8
SigLIP ViT-SO-14 [53]	384^{2}	878.0	83.1	20.0	26.7	60.0	33.3	13.3	66.7	33.3	26.7	53.3	37.0
DFN ViT-H-14 [9]	224^{2}	986.1	83.4	20.0	26.7	73.3	26.7	26.7	66.7	46.7	13.3	53.3	39.3
DFN ViT-H-14 [9]	378^{2}	986.7	84.4	13.3	20.0	53.3	33.3	26.7	66.7	40.0	20.0	40.0	34.8
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EVA01 ViT-g-14 [43]	224^{2}	1136.4	78.5	6.7	26.7	40.0	6.7	13.3	66.7	13.3	13.3	20.0	23.0
EVA02 ViT-bigE-14+ [43]	224^{2}	5044.9	82.0	13.3	20.0	66.7	26.7	26.7	66.7	26.7	20.0	33.3	33.3

#1: Scaling up resolution does not help

#2: Scaling up network helps a little

1	Image Size	Params (M)	IN-1k ZeroShot	0	Q	2	† 1	P	•	\$ 0	A	0	MMVP Average
OpenAI ViT-L-14 [35]	224^{2}	427.6	75.5	13.3	13.3	20.0	20.0	13.3	53.3	20.0	6.7	13.3	19.3
OpenAI ViT-L-14 [35]	336^{2}	427.9	76.6	0.0	20.0	40.0	20.0	6.7	20.0	33.3	6.7	33.3	20.0
SigLIP ViT-SO-14 [53]	224^{2}	877.4	82.0	26.7	20.0	53.3	40.0	20.0	66.7	40.0	20.0	53.3	37.8
SigLIP ViT-SO-14 [53]	384^{2}	878.0	83.1	20.0	26.7	60.0	33.3	13.3	66.7	33.3	26.7	53.3	37.0
DFN ViT-H-14 [9]	224^{2}	986.1	83.4	20.0	26.7	73.3	26.7	26.7	66.7	46.7	13.3	53.3	39.3
OFN ViT-H-14 [9]	378^{2}	986.7	84.4	13.3	20.0	53.3	33.3	26.7	66.7	40.0	20.0	40.0	34.8
MetaCLIP ViT-L-14 [49]	224^{2}	427.6	79.2	13.3	6.7	66.7	6.7	33.3	46.7	20.0	6.7	13.3	23.7
MetaCLIP ViT-H-14 [49]	224^{2}	986.1	80.6	6.7	13.3	60.0	13.3	6.7	53.3	26.7	13.3	33.3	25.2
EVA01 ViT-g-14 [43]	224^{2}	1136.4	78.5	6.7	26.7	40.0	6.7	13.3	66.7	13.3	13.3	20.0	23.0
EVA02 ViT-bigE-14+ [43]	224^{2}	5044.9	82.0	13.3	20.0	66.7	26.7	26.7	66.7	26.7	20.0	33.3	33.3

#1: Scaling up resolution does not help

#2: Scaling up network helps a little

#3: Scaling up data helps a little

1 1 1	Image Size	Params (M)	IN-1k ZeroShot	0	Q	Ø	13	9	•	⊅ °	A	0	MMVI Averag	ge
OpenAI ViT-L-14 [35]	224^{2}	427.6	75.5	13.3	13.3	20.0	20.0	13.3	53.3	20.0	6.7	13.3	19.3	
OpenAI ViT-L-14 [35]	336^{2}	427.9	76.6	0.0	20.0	40.0	20.0	6.7	20.0	33.3	6.7	33.3	20.0	
SigLIP ViT-SO-14 [53]	224^{2}	877.4	82.0	26.7	20.0	53.3	40.0	20.0	66.7	40.0	20.0	53.3	37.8	ł
SigLIP ViT-SO-14 [53]	384^{2}	878.0	83.1	20.0	26.7	60.0	33.3	13.3	66.7	33.3	26.7	53.3	37.0	
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MetaCLIP ViT-H-14 [49]	224^{2}	986.1	80.6	6.7	13.3	60.0	13.3	6.7	53.3	26.7	13.3	33.3	25.2	
EVA01 ViT-g-14 [43]	224^{2}	1136.4	78.5	6.7	26.7	40.0	6.7	13.3	66.7	13.3	13.3	20.0	23.0	
EVA02 ViT-bigE-14+ [43]	224^{2}	5044.9	82.0	13.3	20.0	66.7	26.7	26.7	66.7	26.7	20.0	33.3	33.3	

#1: Scaling up resolution does not help

#3: Scaling up data helps a little

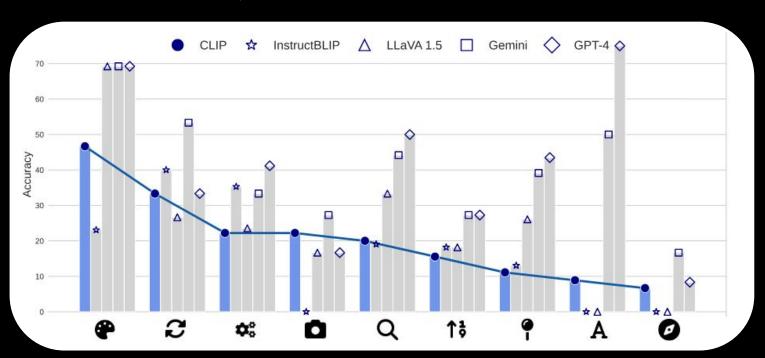
#2: Scaling up network helps a little

#4: All CLIP-variants struggle

1	Image Size	Params (M)	IN-1k ZeroSho	. 0	Q	C	† 1	P	•	ф°	A	Ō	MMVP Average
OpenAI ViT-L-14 [35]	224^{2}	427.6	75.5	13.3	13.3	20.0	20.0	13.3	53.3	20.0	6.7	13.3	19.3
OpenAI ViT-L-14 [35]	336^{2}	427.9	76.6	0.0	20.0	40.0	20.0	6.7	20.0	33.3	6.7	33.3	20.0
SigLIP ViT-SO-14 [53]	224^{2}	877.4	82.0	26.7	20.0	53.3	40.0	20.0	66.7	40.0	20.0	53.3	37.8
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EVA02 ViT-bigE-14+ [43]	224^{2}	5044.9	82.0	13.3	20.0	66.7	26.7	26.7	66.7	26.7	20.0	33.3	33.3

Mistakes in CLIP and MLLM are correlated

The worse CLIP models are, the worse MLLMs are.



What's next?

What's next for more *vision-centric* MLLMs?

- What visual representations to use?
- How to align modalities?
- What data do we train the model?
- How to train the model?
- How do we evaluate and interpret results?

. . .



Cambrian-1 A Fully Open, Vision-Centric Exploration of Multimodal LLMs

Shengbang Tong*, Ellis Brown*, Penghao Wu*, Sanghyun Woo, Manoj Middepogu, Sai Charitha Akula, Jihan Yang, Shusheng Yang, Adithya Iyer, Xichen Pan, Austin Wang, Rob Fergus, Yann LeCun, Saining Xie

New York University



Some Trivia

when did vision develop in animals?



Vision in animals is believed to have developed around 541 million years ago during the Cambrian Explosion a period marked by a rapid diversification of life forms. During this time, the first complex eyes appeared in early arthropods, which likely provided a significant evolutionary advantage by allowing these organisms to better navigate their environments, find food, and avoid predators. This development of vision played a crucial role in the predator-prey dynamics and the overall evolutionary arms race that characterized the Cambrian period.



Visual Representations for MLLMs

How to evaluate visual reprs.?

What visual reprs. to use?



Class Label Supervised ImageNet-1K [105]



A cowboy rides a horse at a rodeo.

Language Supervised CLIP [102]



SSL-Contrastive DINOv2 [96]



SSL-Masking MAE [45]



DiffusionStable Diffusion [104]



Depth Supervised MiDaS [13]



Segmentation Supervised SAM [61]

Visual Representations for MLLMs

Supervision Type	Method	Architecture	Patch Size	Res.	# Tok.	Hidden Size	
Language-Supervised							
Language	OpenAI CLIP	ViT-L	14	336	576	768	
	DFN-CLIP	ViT-L	14	224	256	1024	
	DFN-CLIP	ViT-H	14	378	729	1280	
	EVA-CLIP-02	ViT-L	14	336	576	1024	
	SigLIP	ViT-L	16	384	576	1024	
	SigLIP	ViT-SO400M	14	384	729	1152	
	OpenCLIP	ConvNeXT-L	_	512	¹ 576	1536	
	OpenCLIP	ConvNeXT-L	-	1024	¹ 576	1536	
	OpenCLIP	ConvNeXT-XXL	-	1024	¹ 576	3072	
Self-Supervised	l						
Contrastive	DINOv2	ViT-L	14	336	576	1024	
	DINOv2	ViT-L	14	518	¹ 576	1024	
	MoCo v3	ViT-B	16	224	196	768	
	MoCo v3	ViT-L	16	224	196	1024	
Masked	MAE	ViT-L	16	224	196	1024	
	MAE	ViT-H	14	224	256	1280	
JEPA	I-JEPA	ViT-H	14	224	256	1280	
Other							
Segmentation	SAM	ViT-L	16	1024	¹ 576	1024	
	SAM	ViT-L	16	1024	^I 576	1280	
Depth	MiDaS 3.0	ViT-L	16	384	576	1024	
	MiDaS 3.1	ViT-L	16	518	1024	1024	
Diffusion	Stable Diffusion 2.1	VAE+UNet	16	512	1024	3520	
Class Labels	SupViT	ViT-L	16	224	196	1024	
	SupViT	ViT-H	14	224	256	1280	

23 models!

Evaluation Protocol

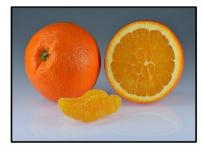
Question: <*image 1*> The region bounded by the graph as shown above. Choose an integral expression that can be used to find the area of R. **Options:**

$$(\underline{\mathbf{A}}) \int_0^{1.5} [f(x) - g(x)] dx$$

(B)
$$\int_0^{1.5} [g(x) - f(x)] dx$$

(C)
$$\int_0^2 [f(x) - g(x)] dx$$

(D)
$$\int_0^2 [g(x) - x(x)] dx$$



Q: what is the color of this object?

A. Purple

B. Pink

C. Gray

D. Orange

GT: D

MMMU [Yue, et al. 2024]



Q: Mention the ZIP code written?

A: 80202

Q: What date is seen on the seal at the top of the letter?

Q: Which company address is mentioned on the letter?

A: Great western sugar Co.



RealWorldQA [Grok, et al. 2024]

MM-Bench [Liu, et al. 2024]



and a lot more...

MMVP [Tong, et al. 2024]

DocVQA [Mathew, et al. 2020]

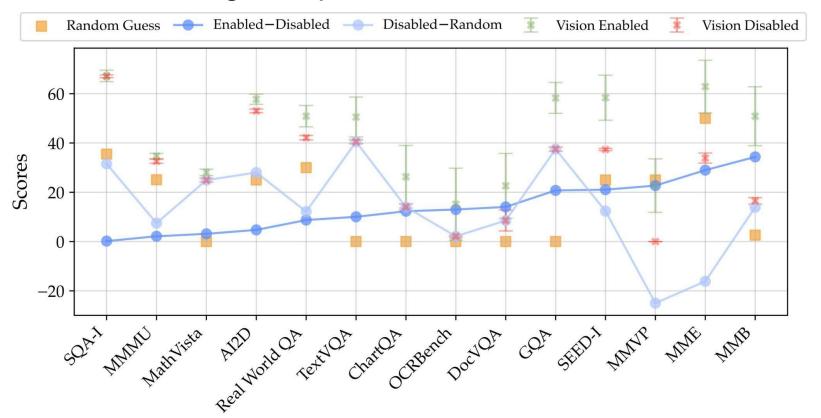
How should we systematically evaluate an MLLM and interpret the evaluation results?

Benchmark Analysis

1. Assess the "Multimodality" of the Benchmarks

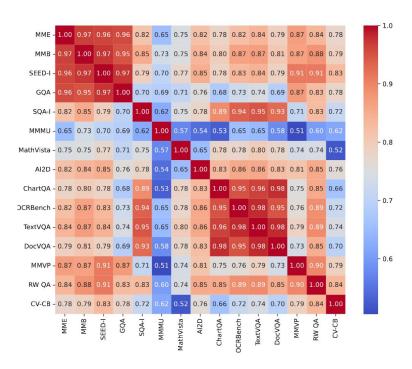
2. Group Benchmarks into Clusters

Who's answering the question: the **LLM** or **MLLM**?

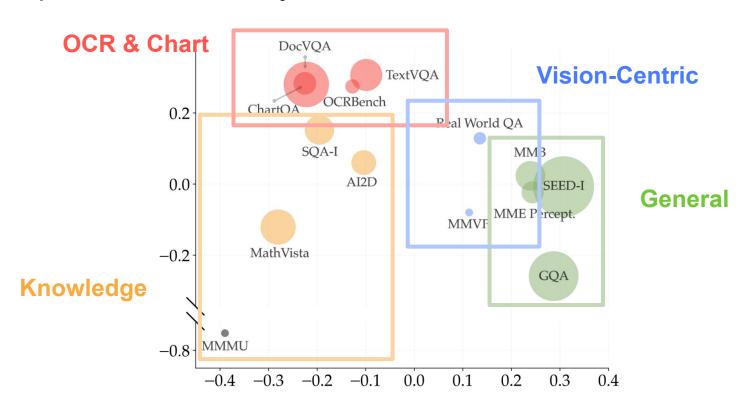


Group Benchmarks by Correlation

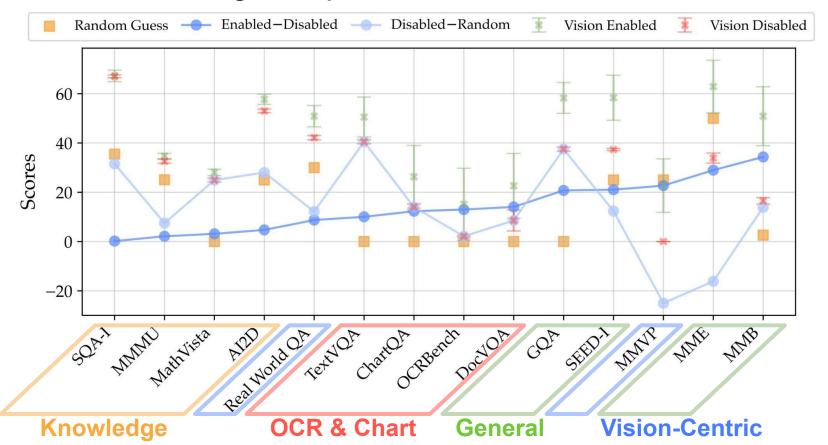
If two benchmarks evaluate on similar domains, they should have a strong correlation



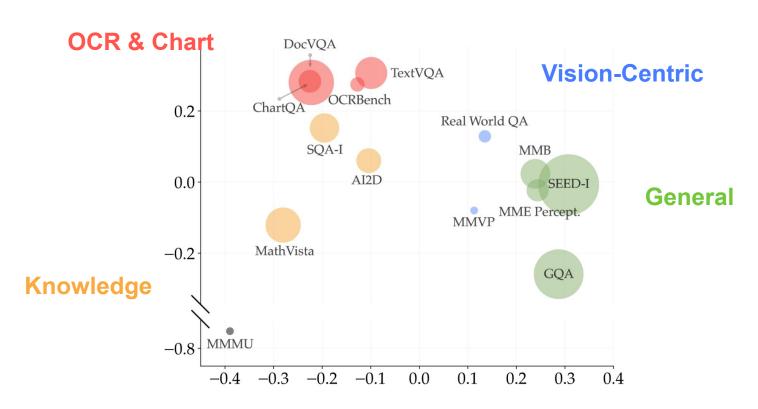
Group Benchmarks by Correlation



Who's answering the question: the **LLM** or **MLLM**?

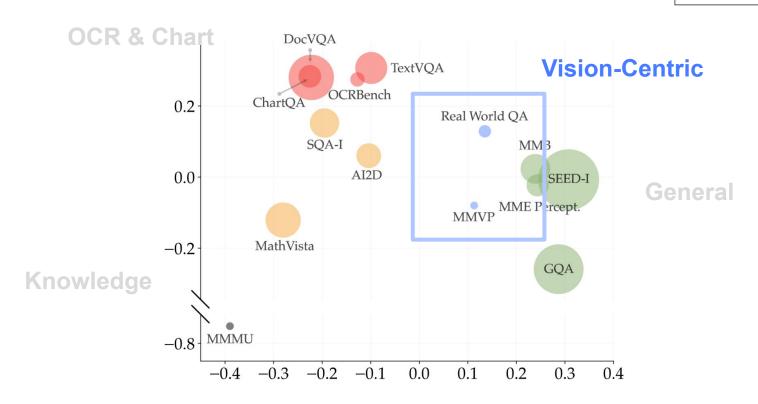


Group Benchmarks by Correlation



Group Benchmarks by Correlation

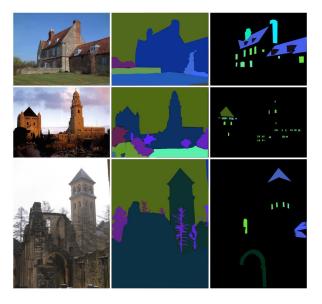
Tiny compared to others!



Q: How can we scalably generate *vision-centric* MLLM evaluations?



Repurpose existing vision datasets!







ADE20K MSCOCO Omni3D

2D

3D

Spatial Relationship



Where is the cave located with respect to the trees?

Object Count



How many cars are in the image?

Depth Order



Which is closer to the camera, sink or pillow?

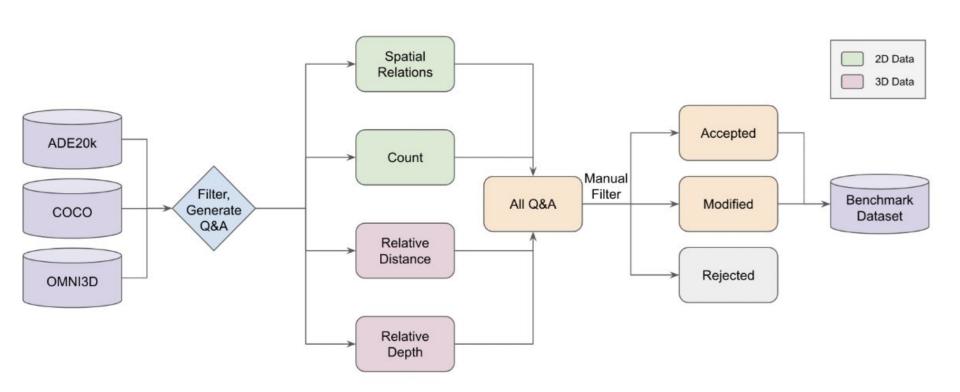
Relative Distance



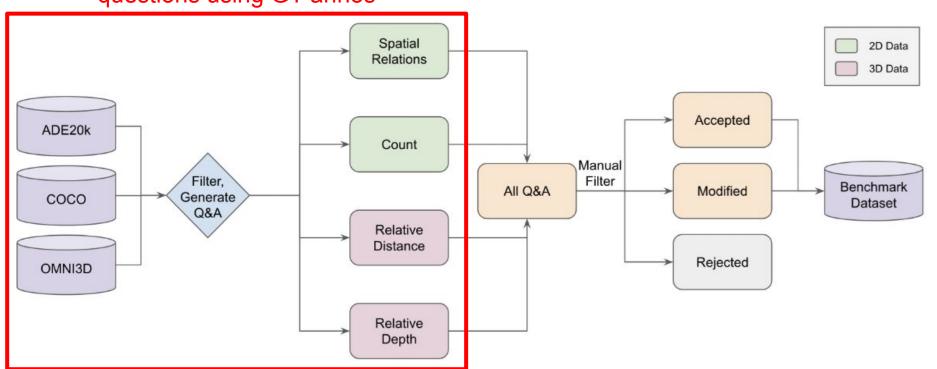
Which is closer to the **chair**, **refrigerator** or **door**?

Source benchmark: ADE20K [145] and COCO [72]

Source benchmark: Omini3D [16]



Programmatically construct VQA questions using GT annos

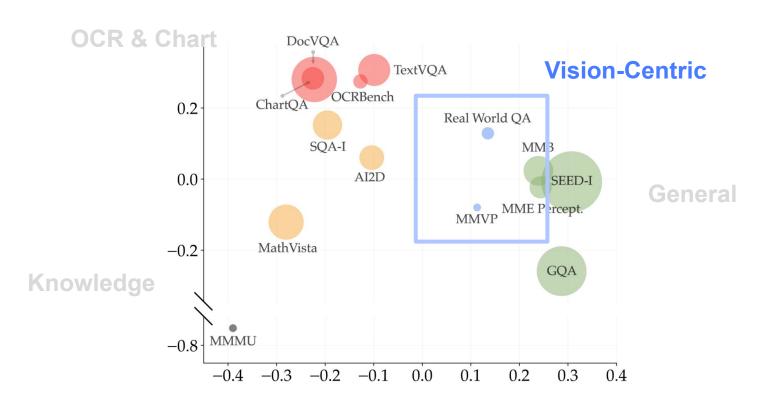


Manually filter <u>all</u> examples Spatial 2D Data Relations 3D Data Accepted ADE20k Count Manual Filter, Filter Benchmark All Q&A Modified Generate COCO Dataset Q&A Relative Distance Rejected OMNI3D Relative Depth

2,638 manually-inspected examples

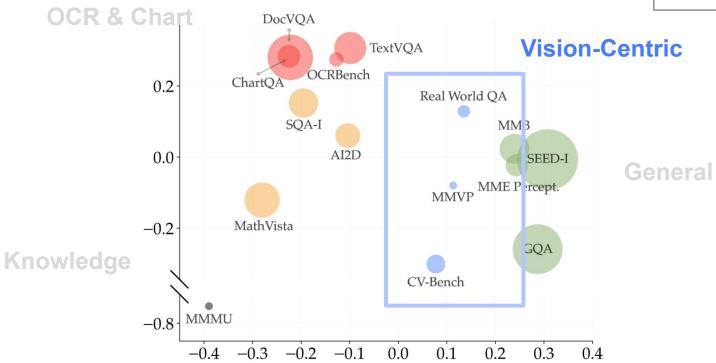
Type	Task	Description	Sources	# Samples
2D	Spatial Relationship	Determine the relative position of an object w.r.t. the anchor object. Consider left-right or top-bottom relationship.	ADE20K COCO	650
	Object Count	Determine the number of instances present in the image.	ADE20K COCO	788
3D	Depth Order	Determine which of the two distinct objects is closer to the camera.	Omni3D	600
	Relative Distance	Determine which of the two distinct objects is closer to the anchor object.	Omni3D	600

Group Benchmarks by Correlation



Group Benchmarks by Correlation

3.5x more vision-centric examples!



Overview







Overview

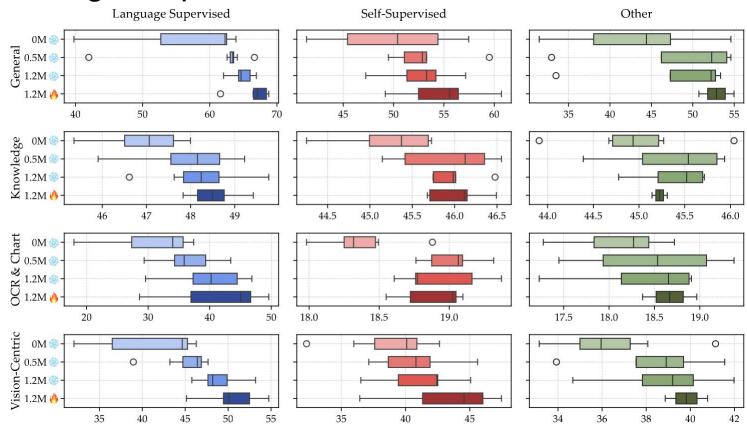




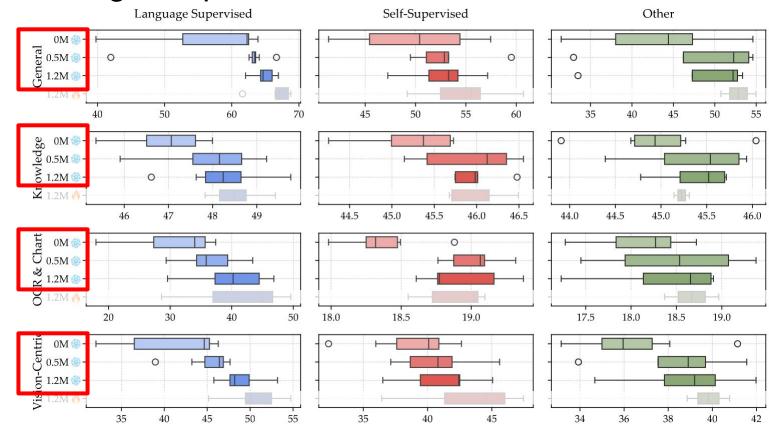


- 1 Stage or 2-Stage Training
 - Training Connector first with Alignment Data?

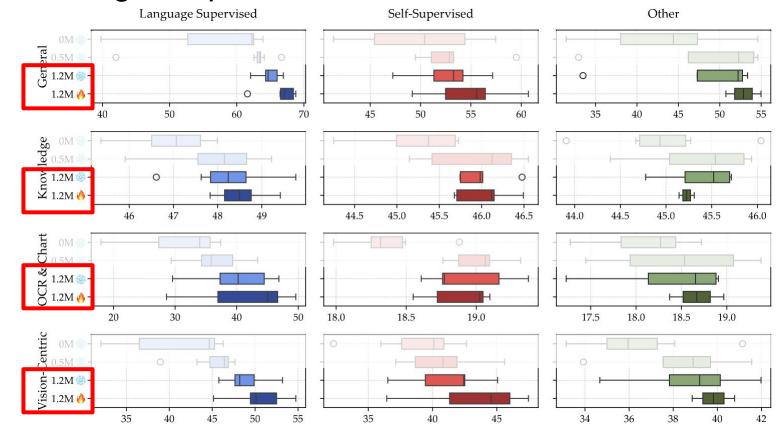
- Freeze or Unfreeze Vision Backbone



More Alignment Data helps!



Unfreezing Vision Encoder Helps



Overview







Instruction Tuning Recipe

Overview

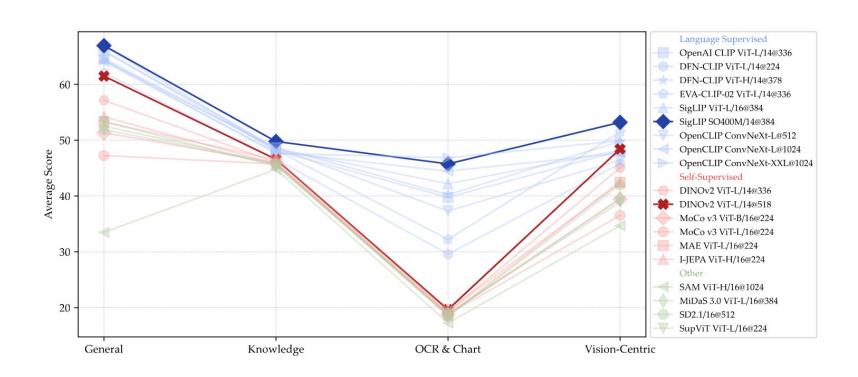




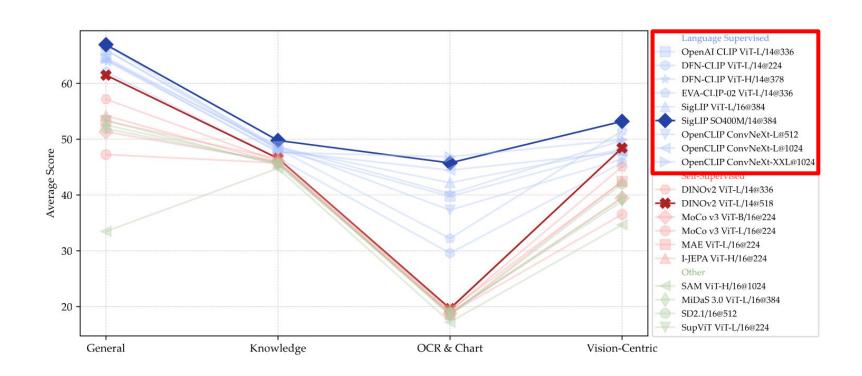


Visual Representations



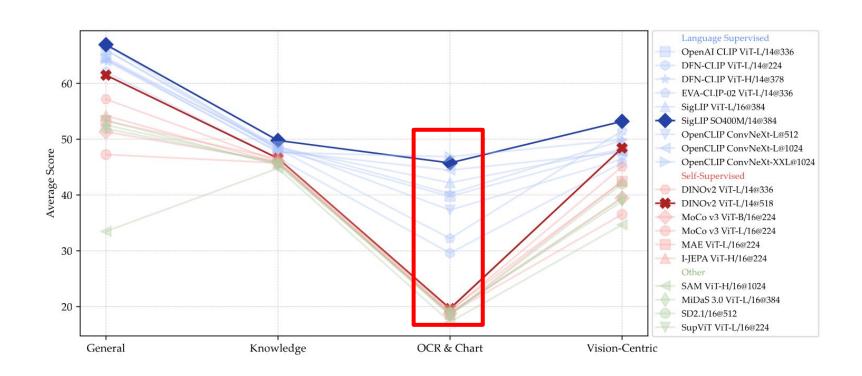


#1 Language Supervised Models are better

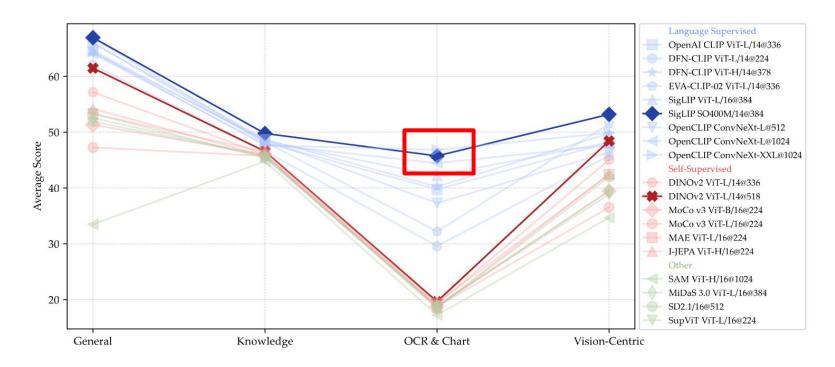


#1 Language Supervised Models are better

#2 Gap is largest in OCR & Chart



#1 Language Supervised Models are better #2 Gap is largest in OCR & Chart #3 ConvNets are good at OCR

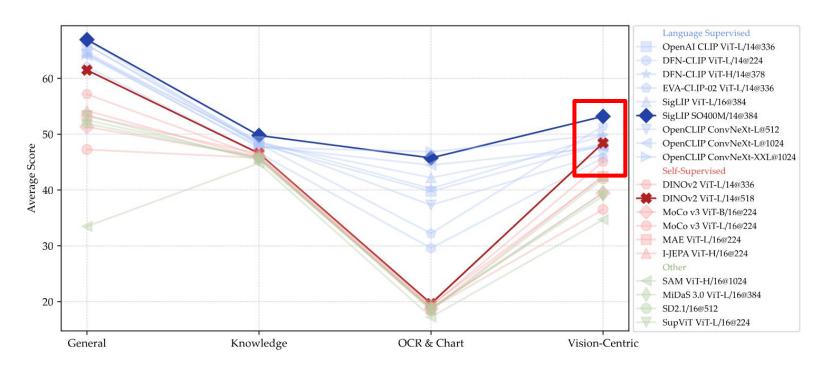


#1 Language Supervised Models are better #2 Gap is largest in OCR & Chart #3 ConvNets are good at OCR

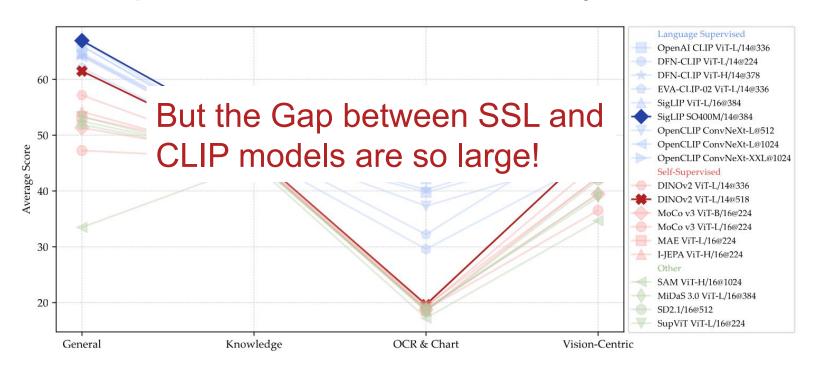
Model	Architecture	All	G	K	O	V
SigLIP	ViT-SO400M/14@384	1	1	1	2	1
OpenCLIP	ConvNeXt-XXL@1024	2	6	8	1	3
DFN-CLIP	ViT-H/14@378	3	4	2	5	4
OpenCLIP	ConvNeXt-L@1024	4	8	7	3	8
SigLIP	ViT-L/16@384	5	5	4	4	6
OpenAI CLIP	ViT-L/14@336	6	3	6	6	7
EVA-CLIP-02	ViT-L/14@336	7	2	5	8	2
OpenCLIP	ConvNeXt-L@512	8	7	3	7	9
DFN-CLIP	ViT-L/14@224	9	9	9	9	10
DINOv2*	ViT-L/14@518	10	10	10	10	5

#1 Language Supervised Models are better #3 ConvNets are good at OCR

#2 Gap is largest in OCR & Chart #4 Best SSL Model good at vision-centric

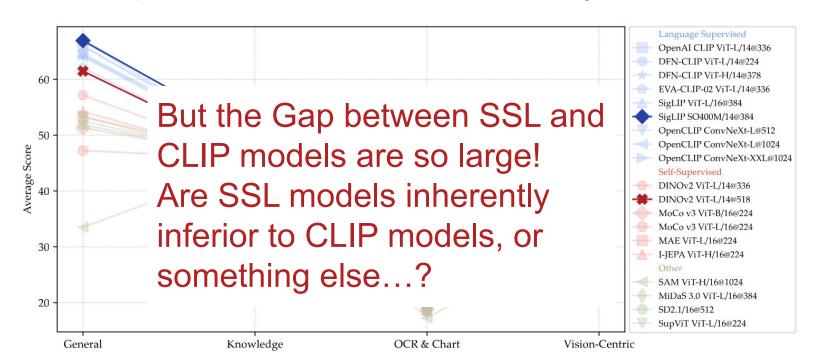


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Visual Representation

#1 Language Supervised Models are better #3 ConvNets are good at OCR #2 Gap is largest in OCR & Chart #4 Best SSL Model good at vision-centric



Scaling Language-Free Visual Representation Learning

David Fan*, Shengbang Tong*, Jiachen Zhu, Koustuv Sinha, Zhuang Liu, Xinlei Chen, Michael Rabbat, Nicolas Ballas, Yann LeCun, Amir Bar†, Saining Xie†

FAIR, Meta, New York University, Princeton University

Visual Representation Learning

Self-Supervision

- MoCo, MAE, DINO
- Learn from images itself (augmentation, masking)
- Train on ImageNet-Like
 Data (million scale to
 hundred million scale)
- Good at <u>classification</u>, segmentation, depth estimation, etc

Language-Supervision:

- CLIP, SigLIP, MetaCLIP
- Learn from language that "describe the text"
- Train on Image-Text pairs crawled from the internet (400 million to 100 billion)
- Good at <u>classification</u>, and widely used at backbone for multimodal models

Visual Representation Learning

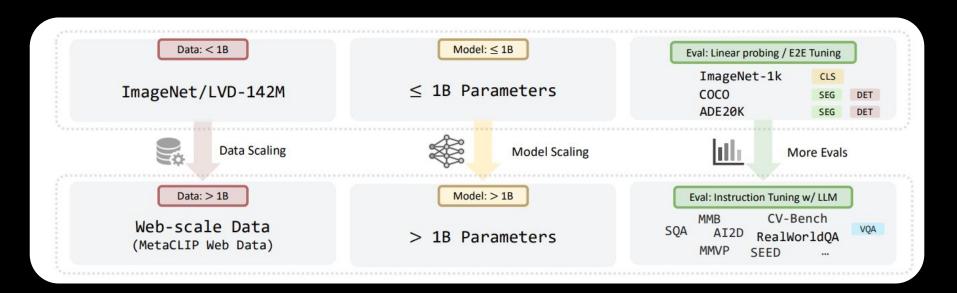
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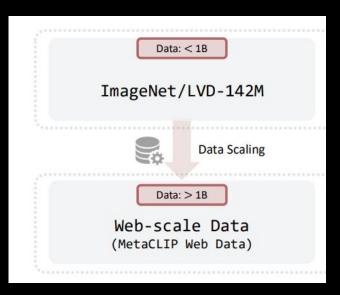
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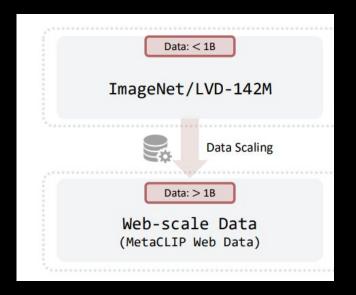
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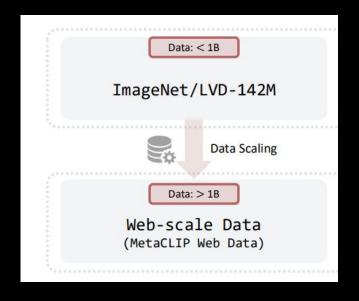
Datasize is at least 10x smaller!







ImageNet/LVD-142M: **Million scale** ImageNet or ImageNet-like distribution, mostly natural images

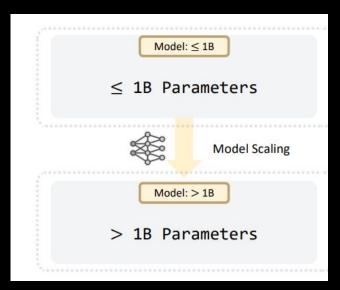


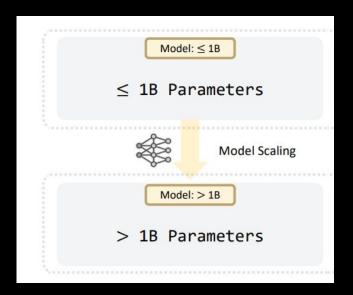
ImageNet/LVD-142M: **Million scale** ImageNet or ImageNet-like distribution, mostly natural images

---->

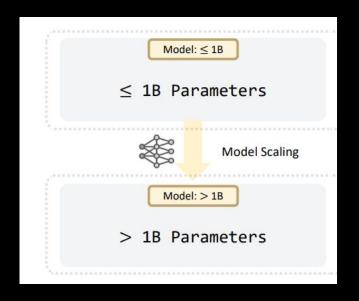
Web-Scale Images (e.g. MetaCLIP): **Billion scale** diverse "random" images from the internet

MetaCLIP-2B: MC-2B





Less than 1B params: ViT-Base, ViT-Large, ViT-Huge, ...



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---->

More than 1B params: ViT-1B, ViT-2B, ViT-3B, ViT-5b, ...





Classic vision eval: classification, segmentation, depth estimation, etc

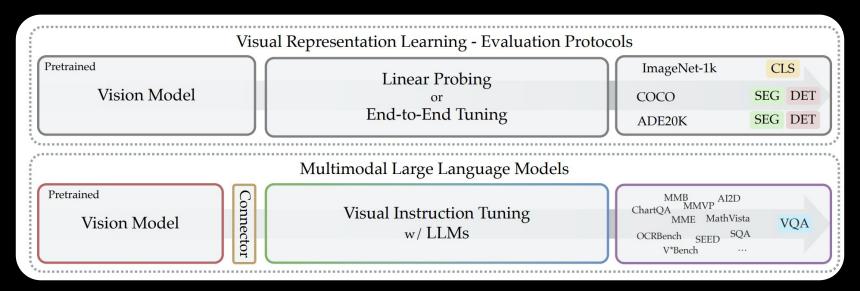


Classic vision eval: classification, segmentation, depth estimation, etc

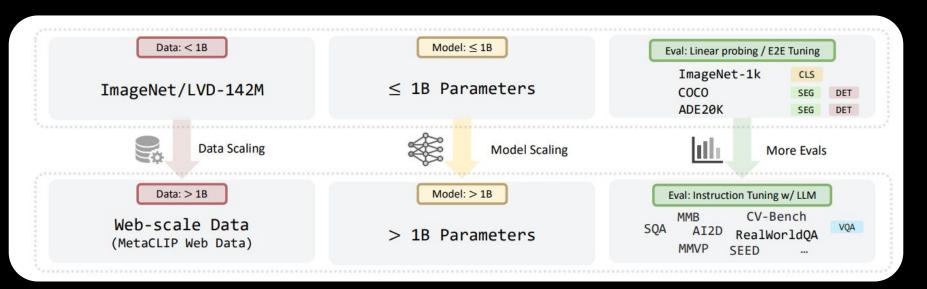
____>

Using VQA as eval: diverser question, more than classic vision tasks

Evaluation Setup



We use Cambrian with *frozen* vision encoder (but finetuned adapter + LLM) to evaluate on VQA tasks: **General**, **Knowledge**, **OCR&Chart**, **Vision-Centric**



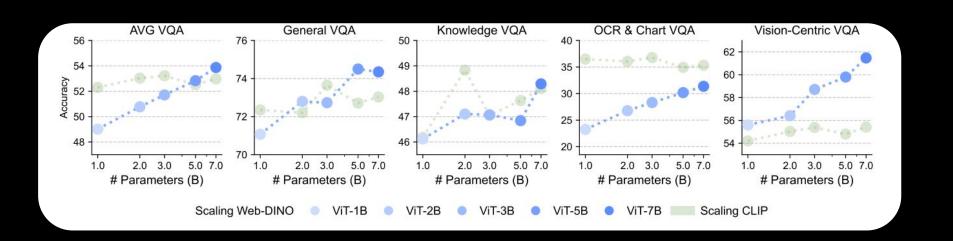
Let's Scale!

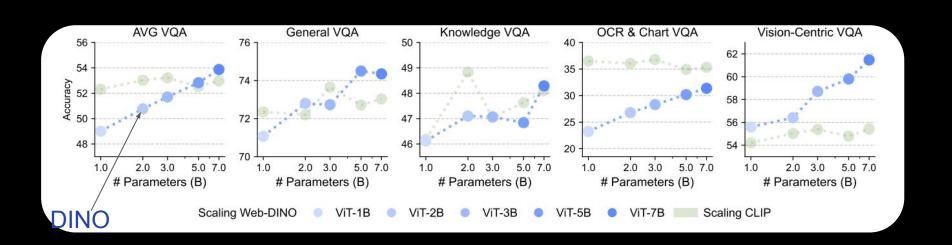
Data: MC-2B, 2 billion samples seen

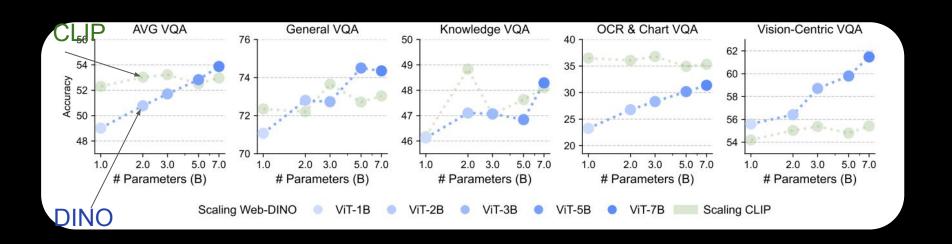
Model: ViT-1B, ViT-2B, ViT-3B, ViT-5B, ViT-7B

Method: DINOv2

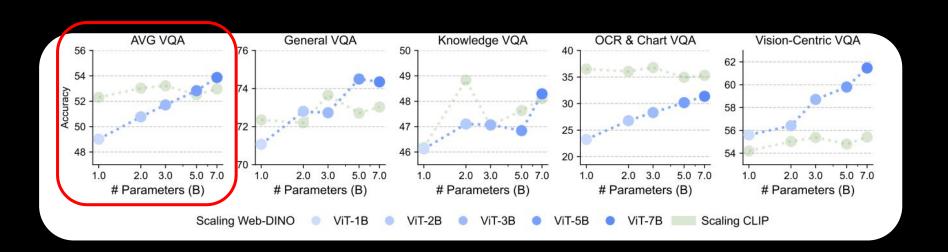
Eval: Use VQA as evaluation.



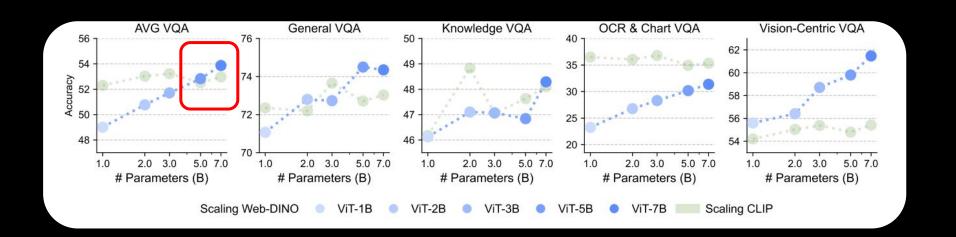




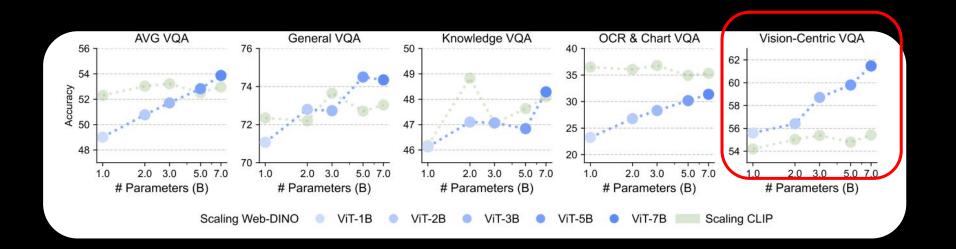
1. Web-DINO scales log-linearly w.r.t to model sizes



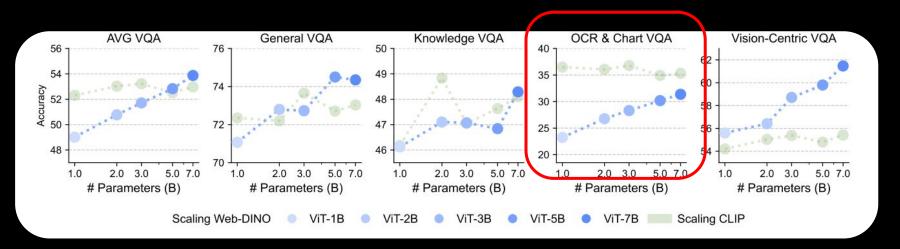
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- 2. Under same conditions, Web-DINO scales better than CLIP



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- 3. Web-DINO continues to excel on Vision-Centric VQA



- 1. Web-DINO scales log-linearly w.r.t to model sizes
- 2. Under same conditions, Web-DINO scales better than CLIP
- 3. Web-DINO continues to excel on Vision-Centric VQA
- The gap on OCR & Chart is closing!



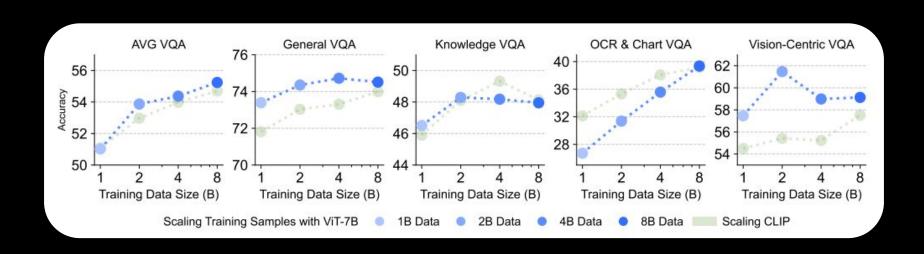
Data: *MC-2B*:

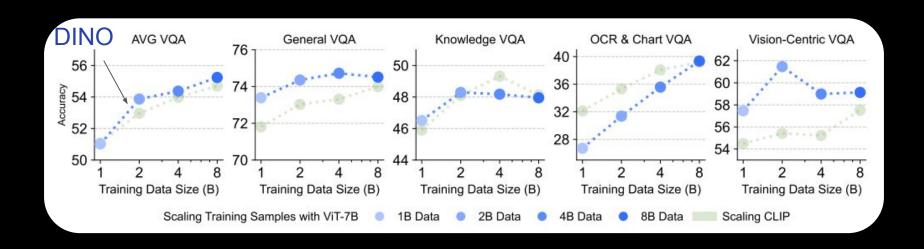
- 1 billion samples seen
- 2 billion samples seen
- 4 billion samples seen
- 8 billion samples seen

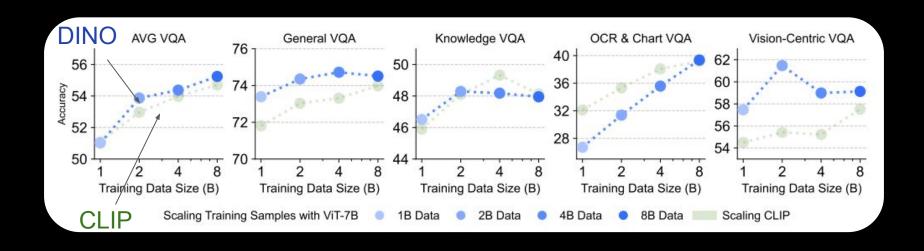
Model: ViT-7B

Method: DINOv2

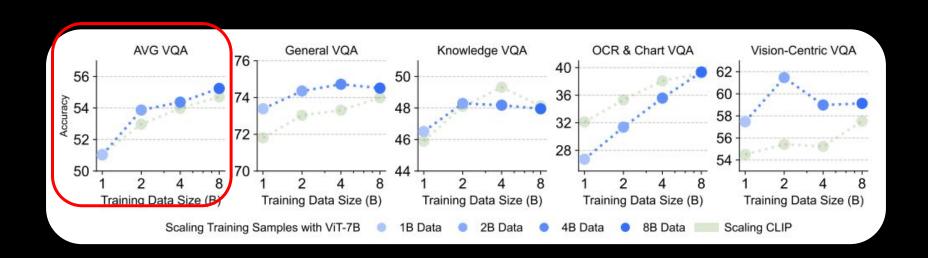
Eval: Use VQA as evaluation.



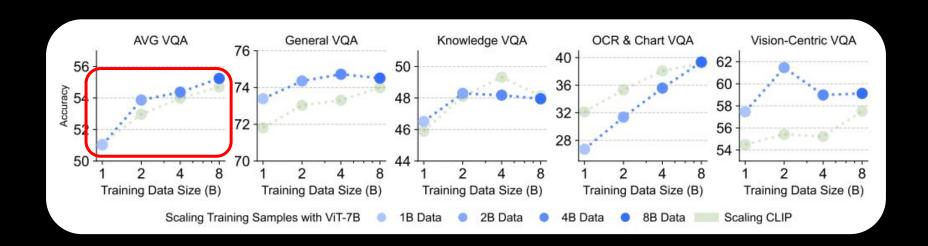




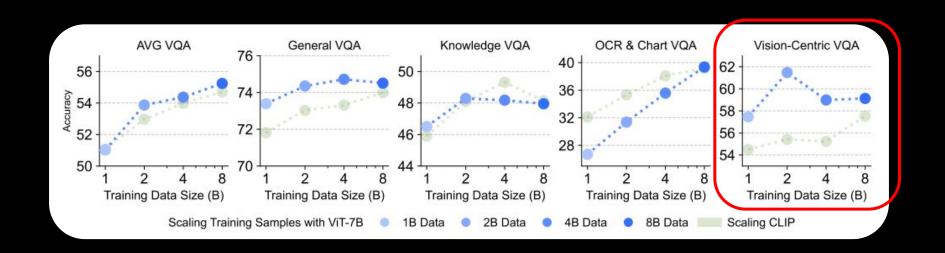
1. Model improves *w.r.t* to more data seen



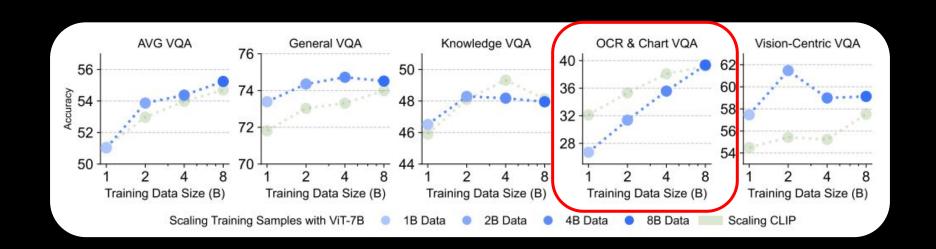
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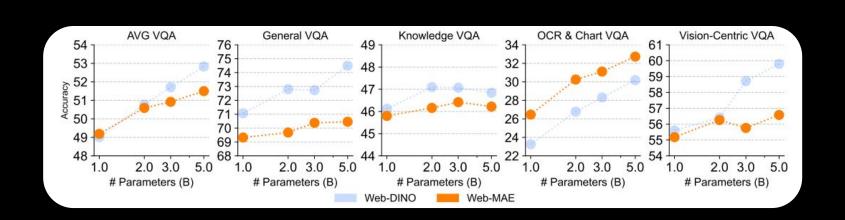
- 1. Model improves w.r.t to more data seen
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- 3. SSL models are better "visual" model
- 4. Gap closes on OCR & Chart.



Q1. Does the observed scaling behavior generalize to other visual SSL methods?

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We conduct similar experiments on MAE And YES!

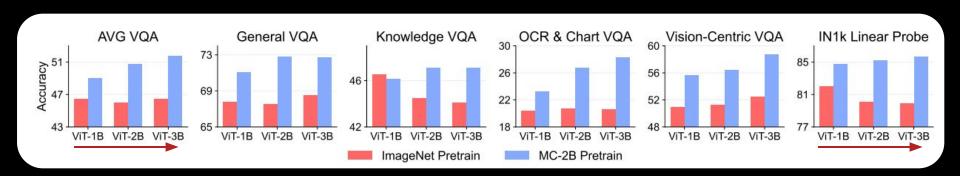


Q2.Does visual SSL exhibit similar scaling behavior on smaller scale conventional data such as ImageNet?

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We conduct similar experiments training on ImageNet-1k

No obvious scaling trend on both VQA and ImageNet-1k



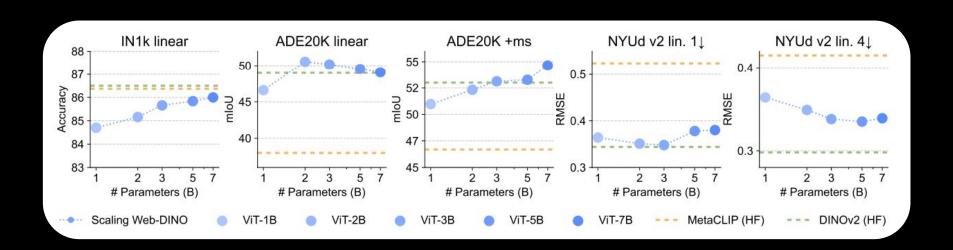
Q3.How do scaled models perform on classic vision tasks?

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Evaluate our trained Web-DINO on classic vision benchmarks

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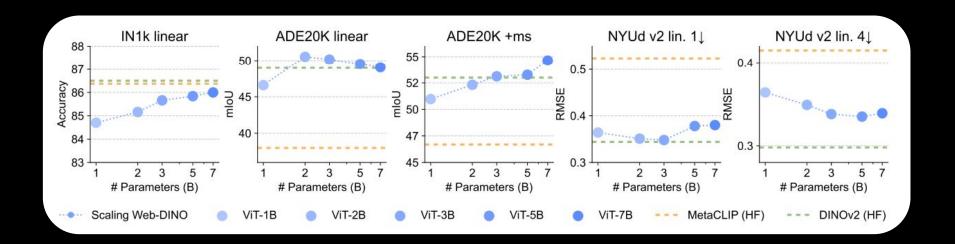
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Q3. How do scaled models perform on classic vision tasks?

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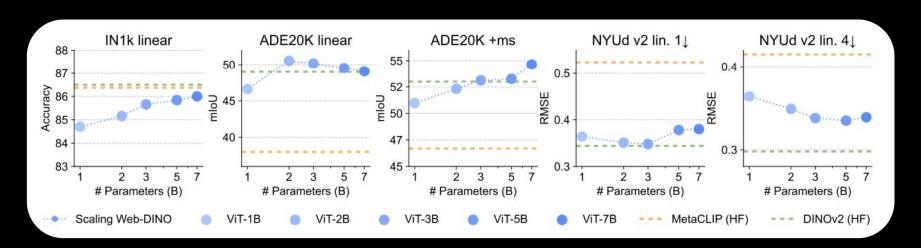
1. Web-DINO is mostly better than MetaCLIP



Q3. How do scaled models perform on classic vision tasks?

Evaluate our trained Web-DINO on classic vision benchmarks

- 1. Web-DINO is mostly better than MetaCLIP
- 2. Web-DINO remains competitive with DINOv2
 - a. Challenging! Since LVD142M is retrieved from classic vision tasks train set.



Hypothesis: Maybe web-scale data contains very rich text information in images, and SSL models can learn from them

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		VQA Evaluator					Breakdown of OCR & Chart Tasks				
Method	% of MC-2B	AVG	General	Knowledge	Vision Centric	OCR Chart	ChartQA	OCRBench	TextVQA	DocVQA	
CLIP 2B		14,011,000,000	72.2	48.8	55.0	36.1	32.8	32.9	52.6	26.0	
Web-DINO 2B	100%	50.8	72.8	47.1	56.4	26.8	23.3	15.6	49.2	19.0	
Web-DINO 2B	50.3%	53.4 (+2.6)	73.0 (+0.2)	51.7 (+4.6)	55.6 (-0.8)	33.2 (+6.4)	31.4 (+8.1)	27.3 (+11.7)	51.3 (+2.1)	23.0 (+4.0)	
Web-DINO 2B	1.3%	53.7 (+2.9)	70.7 (-2.1)	47.3 (+0.2)	56.2 (-0.2)	40.4 (+13.6)	47.5 (+24.2)	29.4 (+13.8)	52.8 (+3.6)	32.0 (+13.0	

Hypothesis: Maybe web-scale data contains very rich text information in images, and SSL models can learn from them

The "text" in images contribute to the OCR & Chart ability and SSL method can learn from it

	1	VQA Evaluator					Breakdown of OCR & Chart Tasks			
	% of				Vision	OCR	Market I have the			
Method	MC-2B	AVG	General	Knowledge	Centric	Chart	ChartQA	OCRBench	TextVQA	DocVQA
CLIP 2B	100%	53.0	72.2	48.8	55.0	36.1	32.8	32.9	52.6	26.0
Veb-DINO 2B	100%	50.8	72.8	47.1	56.4	26.8	23.3	15.6	49.2	19.0
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Hypothesis: SSL models learn features increasingly aligned with language as model size and examples seen increases.

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Measure its alignment with LLM via "Platonic Hypothesis"



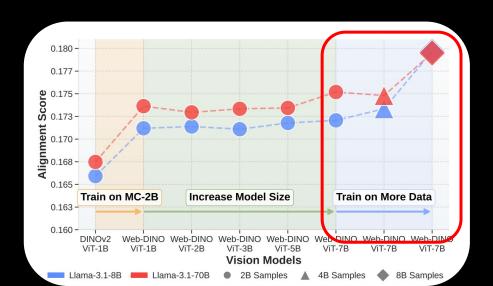
1. Training on more diverse data (MC-2B) lead to better alignment



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- 2. Increase model size gradually lead to better alignment



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- 2. Increase model size gradually lead to better alignment
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As the model scales larger or train longer, it naturally aligns more with LLM



• CLIP models might be the bottleneck in understanding the "visual" world and scaling up does NOT resolve the problem.

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• We need to develop better visual representation

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- Visual SSL are scalable learner: improves w.r.t to model and data sizes when we use VQA as evaluation

 CLIP models might be the bottleneck in understanding the "visual" world and scaling up does NOT resolve the problem.

- We need to develop better visual representation
- Visual SSL are scalable learner: improves w.r.t to model and data sizes when we use VQA as evaluation
- Visual SSL is compatible with CLIP models on VQA, even on OCR & Chart.
 And Visual SSL models are very good at "Vision"

Thank you!